

# The Complexity of Pure Nash Equilibria

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# Definitions

- A **game**: a set of  $n$  players, a set of actions  $S_i$  for each player, and a payoff function  $u_i$  mapping **states** (combinations of actions) to integers for each player
- A **pure Nash equilibrium**: a state such that no player has an incentive to unilaterally change his action
- A **randomized (or mixed) Nash equilibrium**: for each player, a distribution over his states such that no player can improve his expected payoff by changing his action
- A **symmetric game**: a game with all  $S_i$ 's equal, and all  $u_i$ 's identical and symmetric as functions of the other  $n-1$  players

# Context

- Lots of work studying Nash equilibria:
  - Whether they exist
  - What are their properties
  - How they compare to other notions of equilibria
  - etc.
- **But how hard is it to actually find one?**

# Complexity: Randomized NE

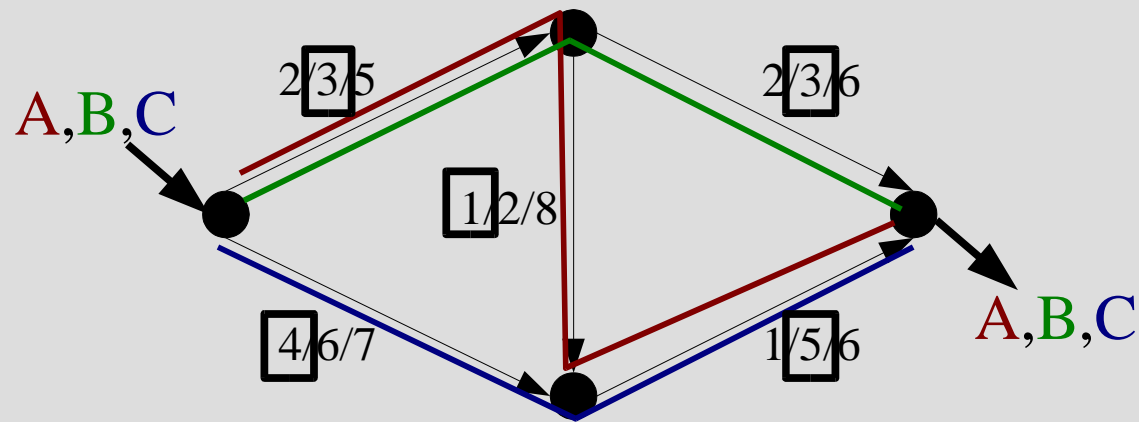
- Nash's theorem guarantees existence of randomized NE, so “find a randomized NE” is a total function, and NP-completeness is out of the question, but:
  - Various slight variations on the problem quickly become NP-Complete [[Conitzer&Sandholm '03](#)]
  - The two-person case has an interesting combinatorial construction, but with exponential counter-examples [[von Stengel '02](#); [Savani&von Stengel '03](#)]
  - It has an “inefficient proof of existence”, placing it in PPAD; other related problems are complete for PPAD, although NE is not known to be [[Papadimitriou '94](#)]

# Complexity: Pure NE

- Natural question: what about pure equilibria?
  - When do they exist?
  - How hard are they to find?
- Immediate problem: with  $n$  players, explicit representations of the payoff functions are exponential in  $n$ ; brute-force search for pure NE is then linear (on the other hand, fixed #players  $\Rightarrow$  boring)
- **Our focus:** The complexity of finding a pure Nash equilibrium in broad *concisely-representable* classes of games

# Congestion games

- Well-studied class of games with clear affinity to networks [Roughgarden&Tardos '02, inter alia]



# Congestion games (cont)

- **General congestion game:**

- finite set  $E$  of resources

- non-decreasing delay function:  $d : E \times \{1, \dots, n\} \rightarrow \mathbb{Z}$

- $S_i$ 's are subsets of  $E$

- Cost for a player:

$$\sum_{e \in S_i} d_e(f_s(e))$$

(number of players using resource  $e$  in state  $s$ )

(delay function for resource  $e$ )

- **Network congestion game:** each edge is a resource, and each player has a source and a sink, with paths forming allowed strategies

# Congestion games & potential functions

- Congestion games have a **potential function**:

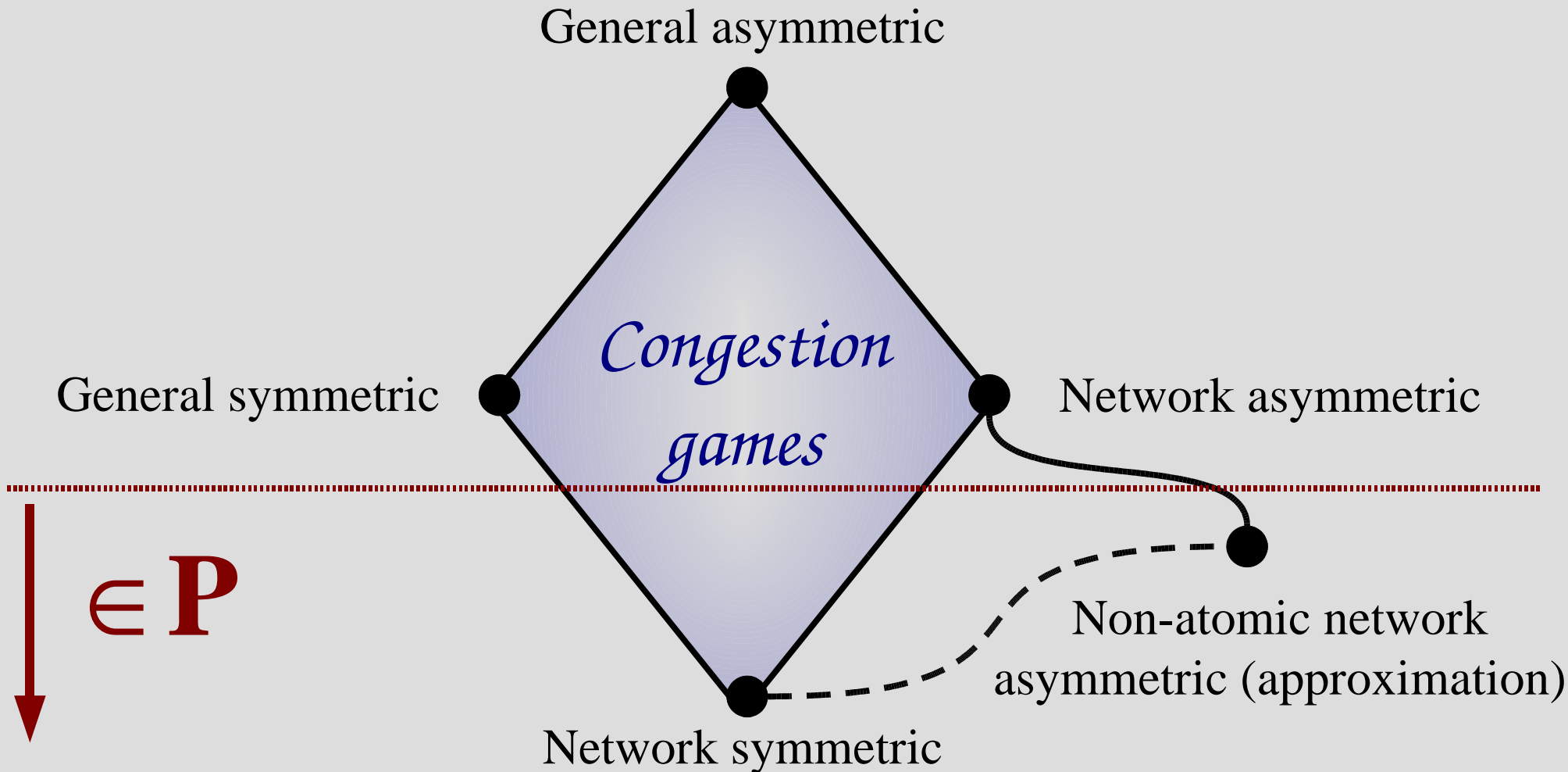
$$\phi(s) = \sum_e \sum_{j=1}^{f_s(e)} d_e(j)$$

If a player changes his strategy, the change in the potential function is **equal** to the change in his payoff

- Local search on potential function guaranteed to converge to a local optimum – an pure NE  
[Rosenthal '73]
- Note: the potential is *not* the social cost

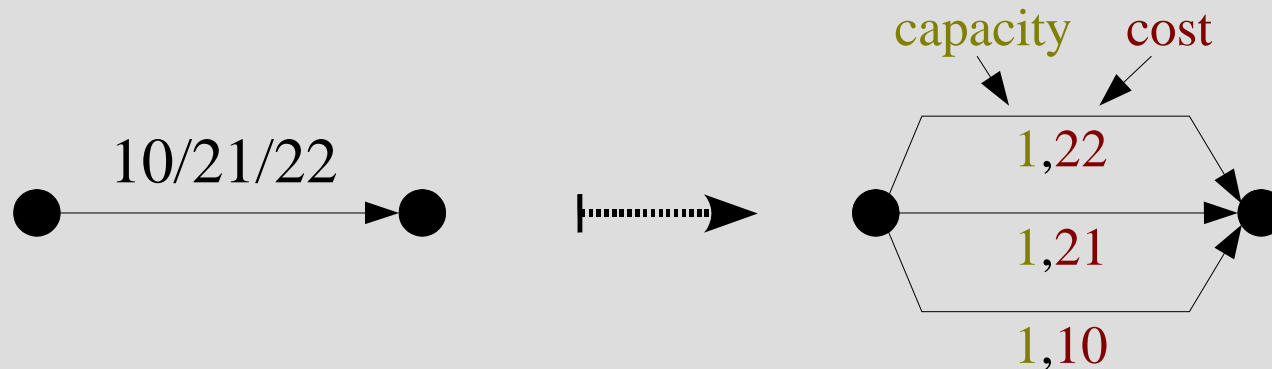


# Our results: upper bounds



# Algorithm: symmetric network games

- Reduction to min-cost-flow: transform each edge into  $n$  edges, with capacities 1, costs  $d_e(1), \dots, d_e(n)$ :

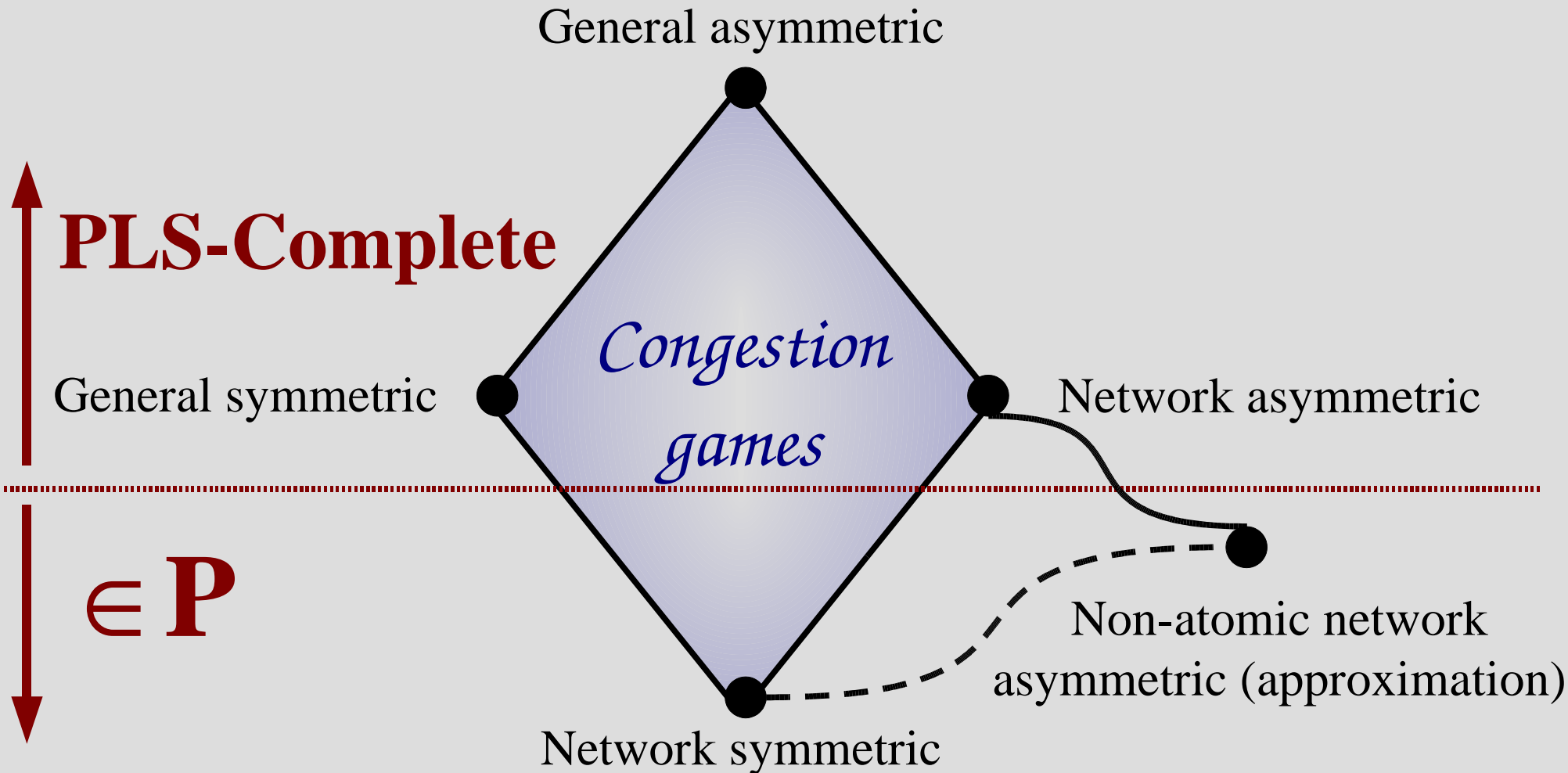


- Integral min-cost flow  $\Rightarrow$  local minimum of potential function

# Algorithm: non-atomic games

- [Roughgarden&Tardos '02] studied *non-atomic* congestion games: what happens when  $n \rightarrow \infty$  (with continuous delay functions)? Can cast as convex optimization, and thus approximate in polynomial time by the ellipsoid method.
- We modify the above to get, in *strongly* polynomial time, approximate pure Nash equilibria (no player can benefit by  $>\epsilon$ ) in the *non-atomic asymmetric network case*
- N.B.: Another strongly-polynomial approximation scheme follows from the OR literature, but it is not clear that it produces approximate Nash equilibria

# Our results: Lower bounds



# P...what?

- **PLS** (polynomial local search [Johnson, et al '88]) – “find **some local minimum** in a reasonable search space”:
  - A **problem with a search space** (a set of feasible solutions which has a neighborhood structure)
  - A poly-time cost function  $c(x,s)$  on the search space
  - A poly-time function that  $g(x,s)$ , given an instance  $x$  and a feasible solution  $s$ , either returns another one in its neighborhood with lower cost or “none” if there are none
- E.g.: “Find a local optimum of a congestion game's potential function under single-player strategy changes”
- Membership in PLS is an inefficient proof of existence

# PLS-Completeness

- PLS reduction:  
(instance<sub>A</sub>, search space<sub>A</sub>)  $\mapsto$  (instance<sub>B</sub>, search space<sub>B</sub>)  
Local optima of A must map to local optima of B
- Basic PLS-Complete problem: weighted CIRCUIT-SAT under input bitflips; since [JPY'88], local-optimum relatives of TSP, MAXCUT, SAT shown PLS-Complete
- We mostly use POS-NAE-3SAT (under input bitflips):  
NAE-3SAT with positive literals only; very complex PLS reduction from CIRCUIT-SAT due to [Schaeffer&Yannakakis '91]

# PLS-Completeness: general asymmetric

- $\text{POS-NAE-3SAT} \leq_{\text{PLS}} \text{General Asymmetric CG}$ :

variable  $x \rightsquigarrow$  player  $x$

clause  $c \rightsquigarrow$  resources  $e_c, e_c'$

$$S_x = \left\{ \left\{ e_c \mid c \ni x \right\}, \left\{ e_c' \mid c \ni x \right\} \right\}$$
$$d_{e_c}(1) = d_{e_c}(2) = 0 \quad ; \quad d_{e_c}(3) = w(c)$$

- Input bitflip maps to a single-player strategy change, with the same change in cost, so search space structure preserved
- $\text{General Asymmetric CG} \leq_{\text{PLS}} \text{General Symmetric CG}$ :
  - “Anonymous” players arbitrarily take on the roles of “non-anonymous” players in the asymmetric game

# PLS-Completeness: general symmetric

- General Asymmetric CG  $\leq_{\text{PLS}}$  General Symmetric CG:
  - Introduce an extra resource  $r_x$  for each player  $x$
  - $d_r(1)=0, d_r(n>1)=\infty$
  - $S = \bigcup_x \{s \cup \{r_x\} \mid s \in S_x\}$
- Same number of players, so any solution that uses an  $r_x$  twice has an unused  $r_x$ , so can't be a local minimum
- Otherwise, players arbitrarily take on the “roles” of players in the original game



# PLS-Completeness: network asymmetric

- First guess: make a network following the idea of the general asymmetric reduction – each POS-NAE-3SAT clause becomes two edges, add extra edges so each variable-player traverses either all  $e_c$  edges, or all the  $e'_c$  edges
- Problem: How do we prevent a player from taking a path that doesn't correspond to a consistent assignment?
- For a dense instance of POS-NAE-3SAT, this appears unavoidable

# PLS-Completeness: network asymmetric

(cont.)

- But: the Schaeffer-Yannakakis reduction produces a very structured, sparse instance of POS-NAE-3SAT
- Our approach:
  - tweak formulae produced by the S-Y reduction
  - carefully arrange the network so “non-canonical” paths are never a good choice
- Details:
  - 39 variable types
  - 124 clause types
  - 3 more talks today
  - full reduction and a sketch of the proof are in the paper

# More on PLS-completeness

- “Clean” PLS reductions: an edge in the original search space corresponds to a short path in the new search space (holds for ours)
- A clean PLS reduction preserves interesting complexity properties (shared by CIRCUIT-SAT, POS-NAE-3SAT, etc):
  - Finding the local optimum reachable from a specific state is PSPACE-complete
  - There are instances with states exponentially far from *any* local optimum

# More on potential functions

- Potential functions clearly relevant to equilibria, so:  
*How applicable is this method?*
- [Monderer&Shapley '96] If *any* game has a potential function, it's equivalent to a (slightly generalized) congestion game
- Party affiliation game:  $n$  players, actions:  $\{-1, 1\}$ , “friendliness” matrix  $\{w_{ij}\}$ . Payoff:  $p(i) = \text{sgn} \sum_j s_i \cdot s_j \cdot w_{ij}$
- Follow the gradient of  $\Phi(s) = \sum_{i,j} s_i \cdot s_j \cdot w_{ij}$  – terminates at a pure NE; but agrees with payoff changes only in sign (and is not a congestion game)

# General potential functions

- Define a *general potential function* as one that agrees just in sign with payoff changes under single-player strategy changes (if one exists, there is a pure NE)
- The problem of finding a pure NE in the presence of such a function is clearly in PLS
- **Theorem:** *Any* problem in PLS corresponds to a family of general potential games with polynomially many players; the set of pure Nash equilibria corresponds exactly to the set of local optima

# Conclusions

- We have:
  1. Given an efficient algorithm for symmetric network congestion games (and an approximation scheme for the non-atomic asymmetric case)
  2. Shown PLS-completeness of both extensions (asymmetry and general congestion game form); “clean” reductions imply other complexity results
  3. Characterized a link between PLS and general potential games
- Congestion games are thus as hard as any other game with pure NEs guaranteed by a general potential function

# Open problems

- Other classes of games where the Nash dynamics converges:
  - Via general potential functions:
    - Basic utility games in [Vetta '02]
    - Congestion games with player-specific delays [Fotakis, et al '02]
  - An algebraic argument shows that the union of 2 games with pure NE's, under some conditions, retains pure NE's
- Acyclic Nash dynamics guarantees *some* potential function (toposort the solution space), but is there always a *tractable* one?
- Pointed out yesterday [Wigderson, yesterday]: complexity classification of games?